Contextuality as a resource

simulations, adaptivity comonad, and the (partial) algebraic-logical view

Rui Soares Barbosa

rui.soaresbarbosa@inl.int



Resources in Computation Workshop University College London 21st September 2022

Based on joint work with Samson Abramsky, Martti Karvonen, Shane Mansfield

Based on joint work with Samson Abramsky, Martti Karvonen, Shane Mansfield

Sheaf-theoretic formalism for contextuality

'The sheaf-theoretic structure of non-locality and contextuality' Abramsky & Brandenburger, New Journal of Physics, 2011.

'Logical Bell inequalities' Abramsky & Hardy, Physical Review A, 2012.

'Contextuality, cohomology, and paradox' Abramsky, B, Kishida, Lal, & Mansfield, CSL 2015.

(cf. Cabello-Severini-Winter, Acín-Fritz-Leverrier-Sainz)

Based on joint work with Samson Abramsky, Martti Karvonen, Shane Mansfield

Resource theory for contextuality

'Contextual fraction as a measure of contextuality' Abramsky, B, Mansfield, Physical Review Letters, 2017.

'*Categories of empirical models*' Karvonen, QPL 2018.

"A comonadic view of simulation and quantum resources" Abramsky, B, Karvonen, Mansfield, LiCS 2019.

'Closing Bell: boxing black box simulations in the resource theory of contextuality' B, Karvonen, Mansfield, in Abramsky on Logic and Structure in CS and Beyond, Springer, 2022.

Based on joint work with Samson Abramsky, Martti Karvonen, Shane Mansfield

Partial Boolean algebras

'The logic of contextuality' Abramsky & B, CSL 2021.

'*Duality for transitive partial CABAs*' Abramsky & B, TACL 2022.

Resource theory via pBAs

ongoing work with Martti Karvonen



Central object of study of quantum information and computation theory: the advantage afforded by quantum resources in information-processing tasks.

Overview

- Central object of study of quantum information and computation theory: the advantage afforded by quantum resources in information-processing tasks.
- A range of examples are known and have been studied ... but a systematic understanding of the scope and structure of quantum advantage is lacking.

Overview

- Central object of study of quantum information and computation theory: the advantage afforded by quantum resources in information-processing tasks.
- A range of examples are known and have been studied ... but a systematic understanding of the scope and structure of quantum advantage is lacking.
- > A hypothesis: this is related to **non-classical** features of quantum mechancics.

Overview

- Central object of study of quantum information and computation theory: the advantage afforded by quantum resources in information-processing tasks.
- A range of examples are known and have been studied ... but a systematic understanding of the scope and structure of quantum advantage is lacking.
- A hypothesis: this is related to **non-classical** features of quantum mechancics.
- Contextuality is a quintessential marker of non-classicality, an empirical phenomenon distinguishing QM from classical physical theories.

- Not all properties may be observed at once.
- Jointly observable properties provide partial snapshots.

- ▶ Not all properties may be observed at once.
- Jointly observable properties provide partial snapshots.



M. C. Escher, Ascending and Descending

- ▶ Not all properties may be observed at once.
- Jointly observable properties provide partial snapshots.









Local consistency

- ▶ Not all properties may be observed at once.
- Jointly observable properties provide partial snapshots.



Local consistency but Global inconsistency

Contextuality and advantage in quantum computation

It has been established as a useful resource conferring quantum advantage in informatic tasks.

Contextuality and advantage in quantum computation

It has been established as a useful resource conferring quantum advantage in informatic tasks.

Measurement-based quantum computation (MBQC)

'Contextuality in measurement-based quantum computation' Raussendorf, Physical Review A, 2013.

Magic state distillation

Contextuality supplies the 'magic' for quantum computation' Howard, Wallman, Veitch, Emerson, Nature, 2014.

Shallow circuits

'*Quantum advantage with shallow circuits*' Bravyi, Gossett, Koenig, Science, 2018.

Contextuality analysis: Aasnæss, Forthcoming, 2020.

► The focus shifts from **objects**...

(empirical models e: S, the behaviours that may be used as resources)

► The focus shifts from **objects**...

(empirical models e: S, the behaviours that may be used as resources)

► to morphisms

(convertions between behaviours)

The focus shifts from **objects**... (empirical models e : S, the behaviours that may be used as resources)

► to morphisms

(convertions between behaviours)

 $d \rightsquigarrow e$ simulation of empirical model e : T using empirical model d : S.

 The focus shifts from **objects**... (empirical models e : S, the behaviours that may be used as resources)

▶ to morphisms

(convertions between behaviours)

 $d \rightsquigarrow e$ simulation of empirical model e : T using empirical model d : S.

• The 'free' operations are given by classical procedures $S \longrightarrow T$.

 The focus shifts from objects... (empirical models e : S, the behaviours that may be used as resources)

▶ to morphisms

(convertions between behaviours)

 $d \rightsquigarrow e$ simulation of empirical model e : T using empirical model d : S.

- The 'free' operations are given by classical procedures $S \longrightarrow T$.
- We first consider non-adaptive procedures,

 The focus shifts from objects... (empirical models e : S, the behaviours that may be used as resources)

to morphisms

(convertions between behaviours)

 $d \rightsquigarrow e$ simulation of empirical model e : T using empirical model d : S.

- The 'free' operations are given by classical procedures $S \longrightarrow T$.
- We first consider non-adaptive procedures,
- > and then capture **adaptivity** via a **comonadic** construction.

Contextuality











 Interaction with system: perform measurements and observe respective outcomes





 Interaction with system: perform measurements and observe respective outcomes





 Interaction with system: perform measurements and observe respective outcomes





 Interaction with system: perform measurements and observe respective outcomes





 Interaction with system: perform measurements and observe respective outcomes







- Some subsets of measurements can be performed together . . .
- but some combinations are forbibben!





- Some subsets of measurements can be performed together . . .
- but some combinations are forbibben!





- Some subsets of measurements can be performed together . . .
- but some combinations are forbibben!



Measurement scenario $S = \langle X_S, \Sigma_S, O_S \rangle$:




Measurement scenario $S = \langle X_S, \Sigma_S, O_S \rangle$:

► X_S is a finite set of **measurements**;

$$X_{\mathcal{S}} = \{\mathbf{x}, \mathbf{y}, \mathbf{z}\},\$$



Measurement scenario $S = \langle X_S, \Sigma_S, O_S \rangle$:

- X_S is a finite set of measurements;
- ▶ O_S = (O_{S,x})_{x∈Xs} specifies for each x ∈ X_S a non-empty set O_{S,x} of allowed outcomes

$$X_{S} = \{x, y, z\}, \quad O_{S,x} = O_{S,y} = O_{S,z} = \{0, 1\},$$



Measurement scenario $S = \langle X_S, \Sigma_S, O_S \rangle$:

- X_S is a finite set of measurements;
- ▶ O_S = (O_{S,x})_{x∈Xs} specifies for each x ∈ X_S a non-empty set O_{S,x} of allowed outcomes
- Σ_S is an abstract simplicial complex on X_S whose faces are the measurement contexts;

$$X_{S} = \{x, y, z\}, \quad O_{S,x} = O_{S,y} = O_{S,z} = \{0, 1\},$$



Measurement scenario $S = \langle X_S, \Sigma_S, O_S \rangle$:

- X_S is a finite set of measurements;
- ▶ O_S = (O_{S,x})_{x∈Xs} specifies for each x ∈ X_S a non-empty set O_{S,x} of allowed outcomes
- Σ_S is an abstract simplicial complex on X_S whose faces are the measurement contexts;
 i.e. a set of subsets of X_s that:
 - contains all singletons:

 $\{x\} \in \Sigma_S$ for all $x \in X_S$;

is downwards closed:

 $\sigma \in \Sigma_S$ and $\tau \subset \sigma$ implies $\tau \in \Sigma_S$.

 $X_{S} = \{x, y, z\}, \quad O_{S,x} = O_{S,y} = O_{S,z} = \{0, 1\},$



Measurement scenario $S = \langle X_S, \Sigma_S, O_S \rangle$:

- X_S is a finite set of measurements;
- ▶ O_S = (O_{S,x})_{x∈Xs} specifies for each x ∈ X_S a non-empty set O_{S,x} of allowed outcomes
- Σ_S is an abstract simplicial complex on X_S whose faces are the measurement contexts;
 i.e. a set of subsets of X_s that:
 - contains all singletons:

 $\{x\} \in \Sigma_S$ for all $x \in X_S$;

is downwards closed:

 $\sigma \in \Sigma_S$ and $\tau \subset \sigma$ implies $\tau \in \Sigma_S$.

 $X_{\mathcal{S}} = \{\mathsf{x}, \mathsf{y}, \mathsf{z}\}, \quad O_{\mathcal{S}, \mathsf{x}} = O_{\mathcal{S}, \mathsf{y}} = O_{\mathcal{S}, \mathsf{z}} = \{0, 1\}, \quad \Sigma_{\mathcal{S}} = \downarrow \{\{\mathsf{x}, \mathsf{y}\}, \{\mathsf{y}, \mathsf{z}\}, \{\mathsf{x}, \mathsf{z}\}\}.$



		(0,0)	(0, 1)	(1, 0)	(1, 1)
Х	у				
У	Ζ				
X	Ζ				















		(0, 0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	³ /8
у	Ζ	3/8	$^{1/8}$	$^{1/8}$	³ /8
x	Ζ	$^{1/8}$	3/8	³ /8	$^{1/8}$



 Behaviour of system is described by measurement statistics

		(0, 0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	3/8
у	Ζ	3/8	$^{1/8}$	$^{1/8}$	³ /8
x	Ζ	1/8	³ /8	³ /8	$^{1/8}$

No-signalling / no-disturbance



 Behaviour of system is described by measurement statistics

		(0, 0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	3/8
у	Ζ	3/8	$^{1/8}$	$^{1/8}$	³ /8
x	Ζ	1/8	³ /8	³ /8	$^{1/8}$

No-signalling / no-disturbance

Marginal distributions agree

 $P(\mathbf{x}, \mathbf{y} \mapsto a, \mathbf{b})$



 Behaviour of system is described by measurement statistics

		(0,0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	³ /8
у	Ζ	3/8	$^{1}/8$	$^{1/8}$	3/8
x	Ζ	1/8	³ /8	3/8	$^{1/8}$

No-signalling / no-disturbance

Marginal distributions agree

 $P(\mathbf{x}, \mathbf{y} \mapsto a, \mathbf{b})$



 Behaviour of system is described by measurement statistics

		(0, 0)	(0, 1)	(1, 0)	(1, 1)
Х	у	³ /8	$^{1/8}$	$^{1/8}$	³ /8
у	Ζ	3/8	$^{1}/8$	$^{1/8}$	³ /8
x	Ζ	$^{1/8}$	3/8	³ /8	1/8

No-signalling / no-disturbance

$$\sum_{b} P(\mathbf{x}, \mathbf{y} \mapsto a, \mathbf{b})$$



 Behaviour of system is described by measurement statistics

		(0,0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	³ /8
у	Ζ	3/8	$^{1}/8$	$^{1/8}$	3/8
x	Ζ	1/8	³ /8	3/8	$^{1/8}$

No-signalling / no-disturbance

$$\sum_{b} P(\mathbf{x}, \mathbf{y} \mapsto a, \mathbf{b})$$



 Behaviour of system is described by measurement statistics

		(0,0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	³ /8
у	Ζ	3/8	$^{1}/8$	$^{1/8}$	3/8
x	Ζ	1/8	3/8	³ /8	$^{1/8}$

No-signalling / no-disturbance

$$\sum_{b} P(\mathbf{x}, \mathbf{y} \mapsto a, b) \qquad P(\mathbf{x}, \mathbf{z} \mapsto a, c)$$



 Behaviour of system is described by measurement statistics

		(0, 0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	1/8	³ /8
у	Ζ	3/8	$^{1}/8$	$^{1/8}$	³ /8
x	Ζ	1/8	3/8	3/8	1/8

No-signalling / no-disturbance

$$\sum_{b} P(\mathbf{x}, \mathbf{y} \mapsto a, b) \qquad P(\mathbf{x}, \mathbf{z} \mapsto a, c)$$



 Behaviour of system is described by measurement statistics

		(0,0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	³ /8
у	Ζ	3/8	$^{1/8}$	$^{1/8}$	³ /8
x	Ζ	1/8	3/8	3/8	1/8

No-signalling / no-disturbance

$$\sum_{b} P(\mathbf{x}, \mathbf{y} \mapsto a, \mathbf{b})$$

$$\sum_{c} P(\mathbf{x}, \mathbf{z} \mapsto a, c)$$



 Behaviour of system is described by measurement statistics

		(0,0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	³ /8
у	Ζ	3/8	$^{1/8}$	$^{1/8}$	³ /8
x	Ζ	1/8	3/8	3/8	1/8

No-signalling / no-disturbance

$$\sum_{b} P(\mathbf{x}, \mathbf{y} \mapsto a, b) = \sum_{c} P(\mathbf{x}, \mathbf{z} \mapsto a, c)$$



 Behaviour of system is described by measurement statistics

		(0,0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	³ /8
у	Ζ	3/8	$^{1/8}$	$^{1/8}$	³ /8
x	Ζ	1/8	3/8	3/8	1/8

No-signalling / no-disturbance

$$\sum_{b} P(\mathbf{x}, \mathbf{y} \mapsto a, b) \qquad \sum_{c} P(\mathbf{x}, \mathbf{z} \mapsto a, c) = P(\mathbf{x} \mapsto a)$$



 Behaviour of system is described by measurement statistics

		(0,0)	(0, 1)	(1, 0)	(1, 1)
Х	у	3/8	$^{1/8}$	$^{1/8}$	3/8
у	Ζ	3/8	$^{1}/8$	$^{1/8}$	3/8
x	Ζ	1/8	³ /8	3/8	$^{1/8}$

No-signalling / no-disturbance

$$\sum_{b} P(\mathbf{x}, \mathbf{y} \mapsto a, b) \qquad \sum_{c} P(\mathbf{x}, \mathbf{z} \mapsto a, c) = P(\mathbf{x} \mapsto a)$$



Empirical model e: S is a family $\{e_{\sigma}\}_{\sigma \in \Sigma_{S}}$ where:

- e_σ is a probability distribution on the set of joint outcomes O_{S,σ} := Π_{x∈σ} O_{S,x}
- These satisfy **no-disturbance**: if $\tau \subset \sigma$, then $e_{\sigma}|_{\tau} = e_{\tau}$.











Non-contextual model



Non-contextual model



 \exists probability distribution d on $\mathbf{O}_{S,X_S} = \prod_{x \in X_S} O_{S,x}$ such that $d|_{\sigma} = e_{\sigma}$ for all $\sigma \in \Sigma_S$.

Contextual model



 \nexists probability distribution d on $\mathbf{O}_{S,X_S} = \prod_{x \in X_S} O_{S,x}$ such that $d|_{\sigma} = e_{\sigma}$ for all $\sigma \in \Sigma_S$.

Resource theory of contextuality

Resource theories



Resource theories



► Consider 'free' (i.e. classical) operations:
Resource theories



 Consider 'free' (i.e. classical) operations: (classical) procedures that use a box of type S to simulate a box of type T



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.
- A deterministic procedure $S \longrightarrow T$ specifies an *S*-experiment ($O_{T,x}$ -valued) for each measurement *x* of *T*.



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.
- A deterministic procedure $S \longrightarrow T$ specifies an *S*-experiment ($O_{T,x}$ -valued) for each measurement *x* of *T*.



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.
- A deterministic procedure $S \longrightarrow T$ specifies an *S*-experiment ($O_{T,x}$ -valued) for each measurement *x* of *T*. (subject to compatibility conditions)



- An O-valued S-experiment is a protocol for an interaction with the box S producing a value in O:
 - which measurements to perform;
 - how to interpret their joint outcome into an outcome in O.
- A deterministic procedure $S \longrightarrow T$ specifies an *S*-experiment ($O_{T,x}$ -valued) for each measurement *x* of *T*. (subject to compatibility conditions)
- A classical procedure is a probabilistic mixture of deterministic procedures.



















































Deterministic procedure $f : S \longrightarrow T$ is $\langle \pi_f, \alpha_f \rangle$:

•
$$\pi_f : \Sigma_T \longrightarrow \Sigma_S$$
 is a simplicial relation:



Deterministic procedure $f : S \longrightarrow T$ is $\langle \pi_f, \alpha_f \rangle$:

- $\pi_f : \Sigma_T \longrightarrow \Sigma_S$ is a simplicial relation:
 - for each $x \in X_T$ specifies $\pi_f(x) \subset X_S$



Deterministic procedure $f: S \longrightarrow T$ is $\langle \pi_f, \alpha_f \rangle$:

- $\pi_f: \Sigma_T \longrightarrow \Sigma_S$ is a simplicial relation:
 - for each $x \in X_T$ specifies $\pi_f(x) \subset X_S$
 - If $\sigma \in \Sigma_T$ then $\pi_f(\sigma) \in \Sigma_S$, where $\pi_f(\sigma) = \bigcup_{x \in \sigma} \pi_f(x)$.



Deterministic procedure $f: S \longrightarrow T$ is $\langle \pi_f, \alpha_f \rangle$:

- $\pi_f: \Sigma_T \longrightarrow \Sigma_S$ is a simplicial relation:
 - for each $x \in X_T$ specifies $\pi_f(x) \subset X_S$
 - If $\sigma \in \Sigma_T$ then $\pi_f(\sigma) \in \Sigma_S$, where $\pi_f(\sigma) = \bigcup_{x \in \sigma} \pi_f(x)$.
- $\alpha_f = (\alpha_{f,x})_{x \in X_T}$ where $\alpha_{f,x} : \mathbf{O}_{S,\pi_f(x)} \longrightarrow O_{T,x}$ maps joint outcomes of $\pi_f(x)$ to outcomes of x.



Deterministic procedure $f: S \longrightarrow T$ is $\langle \pi_f, \alpha_f \rangle$:

- $\pi_f: \Sigma_T \longrightarrow \Sigma_S$ is a simplicial relation:
 - for each $x \in X_T$ specifies $\pi_f(x) \subset X_S$
 - If $\sigma \in \Sigma_T$ then $\pi_f(\sigma) \in \Sigma_S$, where $\pi_f(\sigma) = \bigcup_{x \in \sigma} \pi_f(x)$.
- $\alpha_f = (\alpha_{f,x})_{x \in X_T}$ where $\alpha_{f,x} : \mathbf{O}_{S,\pi_f(x)} \longrightarrow O_{T,x}$ maps joint outcomes of $\pi_f(x)$ to outcomes of x.

Probabilistic procedure $f : S \longrightarrow T$ is $f = \sum_{i} r_i f_i$ where $r_i \ge 0$, $\sum_{i} r_i = 1$, and $f_i : S \longrightarrow T$ deterministic procedures.

Classical simulations

> A classical procedure induces a (convex-preserving) map between empirical models:



 $\operatorname{Emp}(f) : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$



Classical simulations

> A classical procedure induces a (convex-preserving) map between empirical models:



Which black-box transformations arise in this fashion?

Characterising classical transformations

Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by a classical procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?



Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an experimental procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?



Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an experimental procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?

Special case S = I



Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an experimental procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?

Special case S = I

Given $F : \operatorname{Emp}(I) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an classical procedure? I.e. is there a procedure $f : I \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?



Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an experimental procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?

Special case S = I

Given $F : \{\star\} \longrightarrow \operatorname{Emp}(T)$, can it be realised by an classical procedure? I.e. is there a procedure $f : I \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?



Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an experimental procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?

Special case S = I

Given an empirical model $e \in \text{Emp}(T)$, can it be realised by an classical procedure? I.e. is there a procedure $f : I \longrightarrow T$ s.t. F = Emp(f)?


Relativising contextuality

Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an experimental procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?

Special case S = I

Given an empirical model $e \in \text{Emp}(T)$, is it noncontextual?



Relativising contextuality

Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an experimental procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?

Special case S = I

Given an empirical model $e \in \text{Emp}(T)$, is it noncontextual? (Non-contextual models are those which can be simulated from nothing.)



From objects to morphisms

Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an classical procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?

is special case of

Given an empirical model, is it noncontextual?

From objects to morphisms ... and back!

Given $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$, can it be realised by an classical procedure? I.e. is there a procedure $f : S \longrightarrow T$ s.t. $F = \operatorname{Emp}(f)$?



Given an empirical model, is it noncontextual?





From two scenarios S and T, we build a new scenario [S, T].



A convex preserving $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$





A convex preserving $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$ induces a canonical model $e_F : [S, T]$.







A convex preserving $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$ induces a canonical model $e_F : [S, T]$. *F* is realised by a deterministic procedure



A convex preserving $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$ induces a canonical model $e_F : [S, T]$.

F is realised by a deterministic procedure iff e_F is deterministic.



A convex preserving $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$ induces a canonical model $e_F : [S, T]$.

F is realised by a deterministic procedure iff e_F is deterministic.

F is realised by a classical procedure iff e_F is non-contextual.



A convex preserving $F : \operatorname{Emp}(S) \longrightarrow \operatorname{Emp}(T)$ induces a canonical model $e_F : [S, T]$. F is realised by a deterministic procedure iff e_F is deterministic and satisfies $g_{[S,T]}$. F is realised by a classical procedure iff e_F is non-contextual and satisfies $g_{[S,T]}$.

Two special cases of simulations

• $f: I \longrightarrow T$ from the trivial scenario are **non-contextual** models.

Two special cases of simulations

- $f: I \longrightarrow T$ from the trivial scenario are **non-contextual** models.
- $f: S \longrightarrow 2$ to the single measurement two-outcome scenario is a **predicate**

Two special cases of simulations

- $f: I \longrightarrow T$ from the trivial scenario are **non-contextual** models.
- $f: S \longrightarrow 2$ to the single measurement two-outcome scenario is a **predicate**
 - It induces a map $EMP(S) \longrightarrow [0,1]$ yielding the probability that it holds.

Adaptive simulations

Basic simulations are useful, but limited.

Basic simulations are useful, but limited.

To allow adaptive use of the resource, we introduce measurement protocols.

Basic simulations are useful, but limited.

To allow adaptive use of the resource, we introduce measurement protocols.

These protocols proceed iteratively by first performing a set of measurements over the given scenario, and then conditioning their further measurements on the observed outcomes.

Basic simulations are useful, but limited.

To allow adaptive use of the resource, we introduce measurement protocols.

These protocols proceed iteratively by first performing a set of measurements over the given scenario, and then conditioning their further measurements on the observed outcomes.

Note that different paths can lead into different, incompatible contexts.

Basic simulations are useful, but limited.

To allow adaptive use of the resource, we introduce measurement protocols.

These protocols proceed iteratively by first performing a set of measurements over the given scenario, and then conditioning their further measurements on the observed outcomes.

Note that different paths can lead into different, incompatible contexts.

Thus they incorporate adaptive classical processing, of the kind used e.g. in Measurement-Based Quantum Computing.

Basic simulations are useful, but limited.

To allow adaptive use of the resource, we introduce measurement protocols.

These protocols proceed iteratively by first performing a set of measurements over the given scenario, and then conditioning their further measurements on the observed outcomes.

Note that different paths can lead into different, incompatible contexts.

Thus they incorporate adaptive classical processing, of the kind used e.g. in Measurement-Based Quantum Computing.

Previously considered in:

'A combinatorial approach to nonlocality and contextuality' Acin, Fritz, Leverrier, Sainz, Communications in Mathematical Physics, 2015.

Basic simulations are useful, but limited.

To allow adaptive use of the resource, we introduce measurement protocols.

These protocols proceed iteratively by first performing a set of measurements over the given scenario, and then conditioning their further measurements on the observed outcomes.

Note that different paths can lead into different, incompatible contexts.

Thus they incorporate adaptive classical processing, of the kind used e.g. in Measurement-Based Quantum Computing.

Previously considered in:

'A combinatorial approach to nonlocality and contextuality' Acin, Fritz, Leverrier, Sainz, Communications in Mathematical Physics, 2015.

Formally, we construct a **comonad** MP on the category of empirical models, where MP(e: S) is the model obtained by taking all measurement protocols over the given scenario.

Given a scenario S we build a new scenario MP(S), where:

Given a scenario S we build a new scenario MP(S), where:

 \blacktriangleright measurements are the measurement protocols on S

 $\mathsf{MP}(S) ::= \emptyset \mid (x, f) \quad \text{where } x \in X_S \text{ and } f \colon O_x \longrightarrow \mathsf{MP}(\langle X_S \setminus \{x\}, \mathsf{lk}_{\sigma} \Sigma_S, O_S \rangle).$

Given a scenario S we build a new scenario MP(S), where:

 \blacktriangleright measurements are the measurement protocols on S

 $\mathsf{MP}(S) ::= \emptyset \mid (x, f) \quad \text{where } x \in X_S \text{ and } f \colon O_x \longrightarrow \mathsf{MP}(\langle X_S \setminus \{x\}, \mathsf{lk}_{\sigma} \Sigma_S, O_S \rangle).$

> outcomes are the joint outcomes observed during a run of the protocol

Given a scenario S we build a new scenario MP(S), where:

 \blacktriangleright measurements are the measurement protocols on S

 $\mathsf{MP}(S) ::= \emptyset \mid (x, f) \quad \text{where } x \in X_S \text{ and } f \colon O_x \longrightarrow \mathsf{MP}(\langle X_S \setminus \{x\}, \mathsf{lk}_{\sigma} \Sigma_S, O_S \rangle).$

- > outcomes are the joint outcomes observed during a run of the protocol
- > measurement protocols are compatible if they can be combined consistently

Given a scenario S we build a new scenario MP(S), where:

 \blacktriangleright measurements are the measurement protocols on S

 $\mathsf{MP}(S) ::= \emptyset \mid (x, f) \quad \text{where } x \in X_S \text{ and } f \colon O_x \longrightarrow \mathsf{MP}(\langle X_S \setminus \{x\}, \mathsf{lk}_\sigma \Sigma_S, O_S \rangle).$

- > outcomes are the joint outcomes observed during a run of the protocol
- > measurement protocols are compatible if they can be combined consistently
 - A run is a sequence $\bar{x} = (x_i, o_i)_{i=1}^l$ with $x_i \in X_S$, $o_i \in O_{S, x_i}$
 - $\bullet \ \sigma_{\bar{x}} = \{x_1, x_2, \ldots, x_l\} \in \Sigma_{\mathcal{S}}.$
 - > Two runs (of different protocols) are consistent if they agree on common measurements
 - Protocols {Q₁,..., Q_n} are compatible if for any choice of pairwise consistent runs x̄_i from Q_i, we have ⋃_i σ_{x̄i} ∈ Σ

Given a scenario S we build a new scenario MP(S), where:

 \blacktriangleright measurements are the measurement protocols on S

 $\mathsf{MP}(S) ::= \emptyset \mid (x, f) \quad \text{where } x \in X_S \text{ and } f \colon O_x \longrightarrow \mathsf{MP}(\langle X_S \setminus \{x\}, \mathsf{lk}_\sigma \Sigma_S, O_S \rangle).$

- > outcomes are the joint outcomes observed during a run of the protocol
- measurement protocols are compatible if they can be combined consistently
 - A run is a sequence $\bar{x} = (x_i, o_i)_{i=1}^l$ with $x_i \in X_S$, $o_i \in O_{S, x_i}$

•
$$\sigma_{\bar{x}} = \{x_1, x_2, \ldots, x_l\} \in \Sigma_S.$$

- > Two runs (of different protocols) are consistent if they agree on common measurements
- ▶ Protocols $\{Q_1, \ldots, Q_n\}$ are compatible if for any choice of pairwise consistent runs \bar{x}_i from Q_i , we have $\bigcup_i \sigma_{\bar{x}_i} \in \Sigma$
- Alternatively, multiple measurements at each stage:

$$\mathsf{MP}(S) ::= \emptyset \mid (\sigma, f) \quad \text{where } \sigma \in \Sigma_S \text{ and } f : \prod_{x \in \sigma} \mathcal{O}_x \longrightarrow \mathsf{MP}(\langle X_S \setminus \sigma, \mathsf{lk}_\sigma \Sigma_S, \mathcal{O}_S \rangle).$$

Given a scenario S we build a new scenario MP(S), where:

 \blacktriangleright measurements are the measurement protocols on S

 $\mathsf{MP}(S) ::= \emptyset \mid (x, f) \quad \text{where } x \in X_S \text{ and } f \colon O_x \longrightarrow \mathsf{MP}(\langle X_S \setminus \{x\}, \mathsf{lk}_\sigma \Sigma_S, O_S \rangle).$

- > outcomes are the joint outcomes observed during a run of the protocol
- measurement protocols are compatible if they can be combined consistently
 - A run is a sequence $\bar{x} = (x_i, o_i)_{i=1}^l$ with $x_i \in X_S$, $o_i \in O_{S, x_i}$

•
$$\sigma_{\bar{x}} = \{x_1, x_2, \ldots, x_l\} \in \Sigma_S.$$

- > Two runs (of different protocols) are consistent if they agree on common measurements
- ▶ Protocols $\{Q_1, \ldots, Q_n\}$ are compatible if for any choice of pairwise consistent runs \bar{x}_i from Q_i , we have $\bigcup_i \sigma_{\bar{x}_i} \in \Sigma$
- Alternatively, multiple measurements at each stage:

$$\mathsf{MP}(S) ::= \emptyset \mid (\sigma, f) \quad \text{where } \sigma \in \Sigma_S \text{ and } f : \prod_{x \in \sigma} \mathcal{O}_x \longrightarrow \mathsf{MP}(\langle X_S \setminus \sigma, \mathsf{lk}_\sigma \Sigma_S, \mathcal{O}_S \rangle).$$

Empirical models in S are then naturally lifted to this scenario MP(S).

Empirical models in S are then naturally lifted to this scenario MP(S).

Proposition

MP defines a comonoidal comonad on the category of deterministic classical procedres (and therefore on the category of empirical models).

Roughly: comultiplication MP(S) \longrightarrow MP²(S) by "flattening", unit MP(S) \longrightarrow S, and MP(S $\otimes T$) \longrightarrow MP(S) \otimes MP(T)

General simulations

Given empirical models e and d, a simulation of e by d is a map

 $d\otimes c\longrightarrow e$

in **Emp**_{MP}, the coKleisli category of MP, i.e. a map

 $\mathsf{MP}(d \otimes c) \longrightarrow e$

in **Emp**, for some noncontextual model *c*.

General simulations

Given empirical models e and d, a simulation of e by d is a map

 $d\otimes c\longrightarrow e$

in \mathbf{Emp}_{MP} , the coKleisli category of MP, i.e. a map

 $\mathsf{MP}(d \otimes c) \longrightarrow e$

in **Emp**, for some noncontextual model *c*.

The use of the noncontextual model c allows for classical randomness in the simulation.

General simulations

Given empirical models e and d, a simulation of e by d is a map

 $d\otimes c\longrightarrow e$

in **Emp**_{MP}, the coKleisli category of MP, i.e. a map

 $\mathsf{MP}(d \otimes c) \longrightarrow e$

in **Emp**, for some noncontextual model c.

The use of the noncontextual model c allows for classical randomness in the simulation. We denote the existence of a simulation of e by d as $d \rightsquigarrow e$, read "d simulates e".

The (partial algebraic) logical view

Algebra of predicates

- ► For simplicity, we make two restrictions to the kind of scenarios we consider:
 - ▶ all measurements are dichotomic: they have two outcomes 0 and 1 (think of true and false).
 - only consider graphical measurement scena
► For simplicity, we make two restrictions to the kind of scenarios we consider:

- all measurements are dichotomic: they have two outcomes 0 and 1 (think of true and false).
- only consider graphical measurement scena
- We can now think of predicates $f: S \longrightarrow 2$ as new measurements:

- ▶ For simplicity, we make two restrictions to the kind of scenarios we consider:
 - ▶ all measurements are dichotomic: they have two outcomes 0 and 1 (think of true and false).
 - only consider graphical measurement scena
- We can now think of predicates $f: S \longrightarrow 2$ as new measurements:
 - ▶ a measurement $x \in X_S$ is represented by the predicate $\star \longrightarrow x$ on inputs, and *id* on outputs.

- ► For simplicity, we make two restrictions to the kind of scenarios we consider:
 - ▶ all measurements are dichotomic: they have two outcomes 0 and 1 (think of true and false).
 - only consider graphical measurement scena
- We can now think of predicates $f: S \longrightarrow 2$ as new measurements:
 - ▶ a measurement $x \in X_S$ is represented by the predicate $\star \longrightarrow x$ on inputs, and *id* on outputs.
 - ▶ given a measurement $x \in X_S$, we can consider a predicate $\neg x$ mapping $\star \longrightarrow x$ on inputs, and \neg on outputs.

- ► For simplicity, we make two restrictions to the kind of scenarios we consider:
 - ▶ all measurements are dichotomic: they have two outcomes 0 and 1 (think of true and false).
 - only consider graphical measurement scena
- We can now think of predicates $f: S \longrightarrow 2$ as new measurements:
 - ▶ a measurement $x \in X_S$ is represented by the predicate $\star \longrightarrow x$ on inputs, and *id* on outputs.
 - ▶ given a measurement $x \in X_S$, we can consider a predicate $\neg x$ mapping $\star \longrightarrow x$ on inputs, and \neg on outputs.
 - given compatible measurements $x, y \in X_S$, we can build $x \lor y$ and $x \land y$.

- ► For simplicity, we make two restrictions to the kind of scenarios we consider:
 - ▶ all measurements are dichotomic: they have two outcomes 0 and 1 (think of true and false).
 - only consider graphical measurement scena
- We can now think of predicates $f : S \longrightarrow 2$ as new measurements:
 - ▶ a measurement $x \in X_S$ is represented by the predicate $\star \longrightarrow x$ on inputs, and *id* on outputs.
 - ▶ given a measurement $x \in X_S$, we can consider a predicate $\neg x$ mapping $\star \longrightarrow x$ on inputs, and \neg on outputs.
 - given compatible measurements $x, y \in X_S$, we can build $x \lor y$ and $x \land y$.
- ► ~→ partial Boolean algebras.

Traditional quantum logic



Birkhoff & von Neumann (1936), 'The logic of quantum mechanics'.

▶ The lattice P(H), of projectors on a Hilbert space H, as a non-classical logic for QM.

Traditional quantum logic



Birkhoff & von Neumann (1936), 'The logic of quantum mechanics'.

- The lattice P(H), of projectors on a Hilbert space H, as a non-classical logic for QM.
- Interpret \land (infimum) and \lor (supremum) as logical operations.

Traditional quantum logic



Birkhoff & von Neumann (1936), 'The logic of quantum mechanics'.

- ▶ The lattice P(H), of projectors on a Hilbert space H, as a non-classical logic for QM.
- Interpret \land (infimum) and \lor (supremum) as logical operations.
- Distributivity fails: $p \land (q \lor r) \neq (p \land q) \lor (p \land r)$.

Traditional quantum logic



Birkhoff & von Neumann (1936), 'The logic of quantum mechanics'.

- ▶ The lattice P(H), of projectors on a Hilbert space H, as a non-classical logic for QM.
- Interpret \land (infimum) and \lor (supremum) as logical operations.
- Distributivity fails: $p \land (q \lor r) \neq (p \land q) \lor (p \land r)$.
- ► Only commuting measurements can be performed together. So, what is the operational meaning of p ∧ q, when p and q do not commute?

An alternative approach



Kochen & Specker (1965), 'The problem of hidden variables in quantum mechanics'.

An alternative approach



Kochen & Specker (1965), 'The problem of hidden variables in quantum mechanics'.

- > The seminal work on contextuality used partial Boolean algebras.
- Only admit physically meaningful operations.
- Represent incompatibility by partiality.

An alternative approach



Kochen & Specker (1965), 'The problem of hidden variables in quantum mechanics'.

- > The seminal work on contextuality used partial Boolean algebras.
- Only admit physically meaningful operations.
- Represent incompatibility by partiality.

Kochen (2015), 'A reconstruction of quantum mechanics'.

▶ Kochen develops a large part of foundations of quantum theory in this framework.

Boolean algebras

Boolean algebra
$$\langle A, 0, 1, \neg, \lor, \land \rangle$$
:

► a set A

- ▶ constants $0, 1 \in A$
- ▶ a unary operation $\neg : A \longrightarrow A$
- binary operations $\lor, \land : A^2 \longrightarrow A$

Boolean algebras

Boolean algebra
$$\langle A, 0, 1, \neg, \lor, \land \rangle$$
:

a set A

- ▶ constants $0, 1 \in A$
- ▶ a unary operation $\neg : A \longrightarrow A$
- binary operations $\lor, \land : A^2 \longrightarrow A$

satisfying the usual axioms: $\langle A, \lor, 0 \rangle$ and $\langle A, \land, 1 \rangle$ are commutative monoids, \lor and \land distribute over each other, $a \lor \neg a = 1$ and $a \land \neg a = 0$.

E.g.: $\langle \mathcal{P}(X), \emptyset, X, \cup, \cap \rangle$, in particular $\mathbf{2} = \{0, 1\} \cong \mathcal{P}(\{\star\})$.

Partial Boolean algebra $\langle A, \odot, 0, 1, \neg, \lor, \land \rangle$:

- ► a set A
- \blacktriangleright a reflexive, symmetric binary relation \odot on A, read commeasurability or compatibility
- ▶ constants $0, 1 \in A$
- (total) unary operation $\neg : A \longrightarrow A$
- (partial) binary operations $\lor, \land : \odot \longrightarrow A$

Partial Boolean algebra $\langle A, \odot, 0, 1, \neg, \lor, \land \rangle$:

▶ a set A

- \blacktriangleright a reflexive, symmetric binary relation \odot on A, read commeasurability or compatibility
- ▶ constants $0, 1 \in A$
- (total) unary operation $\neg : A \longrightarrow A$
- (partial) binary operations $\lor, \land : \odot \longrightarrow A$

such that every set S of pairwise-commeasurable elements is contained in a set T of pairwise-commeasurable elements which is a Boolean algebra under the restriction of the given operations.

Partial Boolean algebra $\langle A, \odot, 0, 1, \neg, \lor, \land \rangle$:

► a set A

- \blacktriangleright a reflexive, symmetric binary relation \odot on A, read commeasurability or compatibility
- ▶ constants $0, 1 \in A$
- (total) unary operation $\neg : A \longrightarrow A$
- (partial) binary operations $\lor, \land : \odot \longrightarrow A$

such that every set S of pairwise-commeasurable elements is contained in a set T of pairwise-commeasurable elements which is a Boolean algebra under the restriction of the given operations.

E.g.: $P(\mathcal{H})$, the projectors on a Hilbert space \mathcal{H} .

Partial Boolean algebra $\langle A, \odot, 0, 1, \neg, \lor, \land \rangle$:

► a set A

- \blacktriangleright a reflexive, symmetric binary relation \odot on A, read commeasurability or compatibility
- ▶ constants $0, 1 \in A$
- (total) unary operation $\neg : A \longrightarrow A$
- (partial) binary operations $\lor, \land : \odot \longrightarrow A$

such that every set S of pairwise-commeasurable elements is contained in a set T of pairwise-commeasurable elements which is a Boolean algebra under the restriction of the given operations.

E.g.: P(H), the projectors on a Hilbert space H. Conjunction, i.e. meet of projectors, becomes partial, defined only on **commuting** projectors.

Partial Boolean algebra $\langle A, \odot, 0, 1, \neg, \lor, \land \rangle$:

► a set A

- \blacktriangleright a reflexive, symmetric binary relation \odot on A, read commeasurability or compatibility
- ▶ constants $0, 1 \in A$
- (total) unary operation $\neg : A \longrightarrow A$
- (partial) binary operations $\lor, \land : \odot \longrightarrow A$

such that every set S of pairwise-commeasurable elements is contained in a set T of pairwise-commeasurable elements which is a Boolean algebra under the restriction of the given operations.

E.g.: P(H), the projectors on a Hilbert space H. Conjunction, i.e. meet of projectors, becomes partial, defined only on **commuting** projectors.

Morphisms of pBAs are maps preserving commeasurability, and the operations wherever defined. This gives a category **pBA**.

Kochen & Specker (1965).

Let \mathcal{H} be a Hilbert space with dim $\mathcal{H} \geq 3$, and P(\mathcal{H}) its pBA of projectors.

Kochen & Specker (1965).

Let \mathcal{H} be a Hilbert space with dim $\mathcal{H} \geq 3$, and P(\mathcal{H}) its pBA of projectors.

There is **no** pBA homomorphism $P(\mathcal{H}) \longrightarrow \mathbf{2}$.

Kochen & Specker (1965).

Let \mathcal{H} be a Hilbert space with dim $\mathcal{H} \geq 3$, and P(\mathcal{H}) its pBA of projectors.

There is **no** pBA homomorphism $P(\mathcal{H}) \longrightarrow \mathbf{2}$.

Kochen & Specker (1965).

Let \mathcal{H} be a Hilbert space with dim $\mathcal{H} \geq 3$, and P(\mathcal{H}) its pBA of projectors.

There is **no** pBA homomorphism $P(\mathcal{H}) \longrightarrow \mathbf{2}$.

No assignment of truth values to all propositions which respects logical operations on jointly testable propositions.

- **BA** is a full subcategory of **pBA**.
- A is the colimit in **pBA** of the diagem C(A) of its boolean subalgebras.

- **BA** is a full subcategory of **pBA**.
- A is the colimit in **pBA** of the diagem C(A) of its boolean subalgebras.
- Let C(A) be the colimit in **BA** of the same diagram C(A).

- **BA** is a full subcategory of **pBA**.
- A is the colimit in **pBA** of the diagem C(A) of its boolean subalgebras.
- Let C(A) be the colimit in **BA** of the same diagram C(A).
- The cone from C(A) to C(A) is also a cone in **pBA**,
- ▶ hence there is a mediating morphism $A \longrightarrow C(A)$!

- **BA** is a full subcategory of **pBA**.
- A is the colimit in **pBA** of the diagem C(A) of its boolean subalgebras.
- Let $\mathcal{C}(A)$ be the colimit in **BA** of the same diagram $\mathcal{C}(A)$.
- The cone from C(A) to C(A) is also a cone in **pBA**,
- hence there is a mediating morphism $A \longrightarrow C(A)$!

But note that **BA** is an equational variety of algebras over **Set**.

- **BA** is a full subcategory of **pBA**.
- A is the colimit in **pBA** of the diagem C(A) of its boolean subalgebras.
- Let $\mathcal{C}(A)$ be the colimit in **BA** of the same diagram $\mathcal{C}(A)$.
- The cone from C(A) to C(A) is also a cone in **pBA**,
- ▶ hence there is a mediating morphism $A \longrightarrow C(A)$!

But note that **BA** is an equational variety of algebras over **Set**.

As such, it is complete and cocomplete, but it also admits the one-element algebra 1, in which 0 = 1. Note that 1 does **not** have a homomorphism to 2.

- **BA** is a full subcategory of **pBA**.
- A is the colimit in **pBA** of the diagem C(A) of its boolean subalgebras.
- Let $\mathcal{C}(A)$ be the colimit in **BA** of the same diagram $\mathcal{C}(A)$.
- The cone from C(A) to C(A) is also a cone in **pBA**,
- ▶ hence there is a mediating morphism $A \longrightarrow C(A)$!

But note that **BA** is an equational variety of algebras over **Set**.

As such, it is complete and cocomplete, but it also admits the one-element algebra 1, in which 0 = 1. Note that 1 does **not** have a homomorphism to 2.

Thus, if a partial Boolean algebra A has no homomorphism to 2, the colimit of C(A), its diagram of Boolean subalgebras, must be 1.

- **BA** is a full subcategory of **pBA**.
- A is the colimit in **pBA** of the diagem C(A) of its boolean subalgebras.
- Let $\mathcal{C}(A)$ be the colimit in **BA** of the same diagram $\mathcal{C}(A)$.
- The cone from C(A) to C(A) is also a cone in **pBA**,
- hence there is a mediating morphism $A \longrightarrow C(A)$!

But note that **BA** is an equational variety of algebras over **Set**.

As such, it is complete and cocomplete, but it also admits the one-element algebra 1, in which 0 = 1. Note that 1 does **not** have a homomorphism to 2.

Thus, if a partial Boolean algebra A has no homomorphism to 2, the colimit of C(A), its diagram of Boolean subalgebras, must be 1.

We could say that such a diagram is "implicitly contradictory", and in trying to combine all the information in a colimit, we obtain the manifestly contradictory 1.

Contextuality in partial Boolean algebras

An advantage of partial Boolean algebras is that the K-S property provides an intrinsic, logical approach to defining **state-independent contextuality**.

Contextuality in partial Boolean algebras

An advantage of partial Boolean algebras is that the K-S property provides an intrinsic, logical approach to defining **state-independent contextuality**.

But where do states come in?

States

Definition

A state or probability valuation on a partial Boolean algebra A is a map $\nu : A \longrightarrow [0,1]$ such that:

1. $\nu(0) = 0;$

- 2. $\nu(\neg x) = 1 \nu(x);$
- 3. for all $x, y \in A$ with $x \odot y$, $\nu(x \lor y) + \nu(x \land y) = \nu(x) + \nu(y)$.

States

Definition

A state or probability valuation on a partial Boolean algebra A is a map $\nu : A \longrightarrow [0,1]$ such that:

1. $\nu(0) = 0;$

2.
$$\nu(\neg x) = 1 - \nu(x);$$

3. for all
$$x, y \in A$$
 with $x \odot y$, $\nu(x \lor y) + \nu(x \land y) = \nu(x) + \nu(y)$.

Proposition

States can be characterised as the maps $\nu : A \longrightarrow [0,1]$ such that, for every Boolean subalgebra B of A, the restriction of ν to B is a finitely additive probability measure on B.

We can define a state $\nu : A \longrightarrow [0,1]$ to be **probabilistically non-contextual** if ν extends to $\mathcal{C}(A)$; that is, there is a state $\hat{\nu} : \mathcal{C}(A) \longrightarrow [0,1]$ such that $\nu = \hat{\nu} \circ \eta$.

We can define a state $\nu : A \longrightarrow [0,1]$ to be **probabilistically non-contextual** if ν extends to $\mathcal{C}(A)$; that is, there is a state $\hat{\nu} : \mathcal{C}(A) \longrightarrow [0,1]$ such that $\nu = \hat{\nu} \circ \eta$.

By the universal property of $\mathcal{C}(A)$, this is equivalent to asking that there is some Boolean algebra B, morphism $h: A \longrightarrow B$, and state $\hat{\nu}: B \longrightarrow [0, 1]$ such that $\nu = \hat{\nu} \circ \eta$.
We can define a state $\nu : A \longrightarrow [0,1]$ to be **probabilistically non-contextual** if ν extends to $\mathcal{C}(A)$; that is, there is a state $\hat{\nu} : \mathcal{C}(A) \longrightarrow [0,1]$ such that $\nu = \hat{\nu} \circ \eta$.

By the universal property of $\mathcal{C}(A)$, this is equivalent to asking that there is some Boolean algebra B, morphism $h: A \longrightarrow B$, and state $\hat{\nu}: B \longrightarrow [0, 1]$ such that $\nu = \hat{\nu} \circ \eta$.

Note that if A is K-S, C(A) = 1, and there is no state on 1.

Free partial Boolean algebra on a reflexive graph (X_S, \frown) (a 'graphical' measurement scenario).

- Generators $G := \{i(x) \mid x \in X\}.$
- ▶ Pre-terms *P*: closure of *G* under Boolean operations and constants.

Free partial Boolean algebra on a reflexive graph (X_S, \frown) (a 'graphical' measurement scenario).

- Generators $G := \{i(x) \mid x \in X\}.$
- ▶ Pre-terms *P*: closure of *G* under Boolean operations and constants.
- Define inductively:
 - ► a predicate ↓ (definedness or existence)
 - ▶ a binary relation ⊙ (commeasurability)
 - a binary relation \equiv (equivalence)

Free partial Boolean algebra on a reflexive graph (X_S, \frown) (a 'graphical' measurement scenario).

- Generators $G := \{i(x) \mid x \in X\}.$
- ▶ Pre-terms *P*: closure of *G* under Boolean operations and constants.
- Define inductively:
 - ► a predicate ↓ (definedness or existence)
 - ▶ a binary relation ⊙ (commeasurability)
 - a binary relation \equiv (equivalence)

 $\triangleright \ T := \{t \in P \mid t \downarrow\}.$

Free partial Boolean algebra on a reflexive graph (X_S, \frown) (a 'graphical' measurement scenario).

- Generators $G := \{i(x) \mid x \in X\}.$
- ▶ Pre-terms *P*: closure of *G* under Boolean operations and constants.
- Define inductively:
 - ► a predicate ↓ (definedness or existence)
 - ▶ a binary relation ⊙ (commeasurability)
 - a binary relation \equiv (equivalence)
- $\triangleright \ T := \{t \in P \mid t \downarrow\}.$
- ▶ $A[\odot] = T / \equiv$, with obvious definitions for \odot and operations.

$$\frac{x \in X}{i(x)\downarrow} \qquad \frac{x \frown y}{i(x) \odot i(y)}$$

$$\frac{x \in X}{i(x)\downarrow} \qquad \frac{x \frown y}{i(x) \odot i(y)}$$
$$\frac{t \odot u}{0\downarrow, 1\downarrow} \qquad \frac{t \odot u}{t \land u\downarrow, t \lor u\downarrow} \qquad \frac{t\downarrow}{\neg t\downarrow}$$

$$\frac{x \in X}{i(x)\downarrow} \quad \frac{x \frown y}{i(x) \odot i(y)}$$

$$\overline{0\downarrow, 1\downarrow} \quad \frac{t \odot u}{t \land u\downarrow, t \lor u\downarrow} \quad \frac{t\downarrow}{\neg t\downarrow}$$

$$\frac{t\downarrow}{t \odot t, t \odot 0, t \odot 1} \quad \frac{t \odot u}{u \odot t} \quad \frac{t \odot u, t \odot v, u \odot v}{t \land u \odot v, t \lor u \odot v} \quad \frac{t \odot u}{\neg t \odot u}$$

$$\frac{x \in X}{i(x)\downarrow} \quad \frac{x \frown y}{i(x) \odot i(y)}$$

$$\overline{0\downarrow, 1\downarrow} \quad \frac{t \odot u}{t \land u\downarrow, t \lor u\downarrow} \quad \frac{t\downarrow}{\neg t\downarrow}$$

$$\frac{t\downarrow}{t \odot t, t \odot 0, t \odot 1} \quad \frac{t \odot u}{u \odot t} \quad \frac{t \odot u, t \odot v, u \odot v}{t \land u \odot v, t \lor u \odot v} \quad \frac{t \odot u}{\neg t \odot u}$$

$$\frac{t\downarrow}{t \equiv t} \quad \frac{t \equiv u}{u \equiv t} \quad \frac{t \equiv u, u \equiv v}{t \equiv v} \quad \frac{t \equiv u, u \odot v}{t \odot v}$$

$$\begin{aligned} \frac{x \in X}{i(x)\downarrow} & \frac{x \frown y}{i(x) \odot i(y)} \\ \hline \\ \overline{0\downarrow, 1\downarrow} & \frac{t \odot u}{t \land u\downarrow, t \lor u\downarrow} & \frac{t\downarrow}{\neg t\downarrow} \\ \hline \\ \frac{t\downarrow}{t \odot t, t \odot 0, t \odot 1} & \frac{t \odot u}{u \odot t} & \frac{t \odot u, t \odot v, u \odot v}{t \land u \odot v, t \lor u \odot v} & \frac{t \odot u}{\neg t \odot u} \\ \hline \\ \frac{t\downarrow}{t \equiv t} & \frac{t \equiv u}{u \equiv t} & \frac{t \equiv u, u \equiv v}{t \equiv v} & \frac{t \equiv u, u \odot v}{t \odot v} \\ \hline \\ \frac{t(\vec{x}) \equiv_{\text{Bool}} u(\vec{x}), \ \land_{i,j} v_i \odot v_j}{t(\vec{v}) \equiv u(\vec{v})} & \frac{t \equiv t', u \equiv u', t \odot u}{t \land u, t \lor u, t \lor u'} & \frac{t \equiv u}{\neg t \equiv \neg u} \end{aligned}$$

▶ The free pBA on a finite reflexive graph is finite

- ▶ The free pBA on a finite reflexive graph is finite
- ▶ But the pBA (internally) generated by a subset of a pBA A may be infinite: e.g. $P(\mathbb{C}^2 \otimes \mathbb{C}^2)$

- ▶ The free pBA on a finite reflexive graph is finite
- ▶ But the pBA (internally) generated by a subset of a pBA A may be infinite: e.g. $P(\mathbb{C}^2 \otimes \mathbb{C}^2)$
- The reason is that new compatibilities arise!

Given two graphical measurement scenarios:

Simulations $f: S \longrightarrow T$ induce a map $Pred(T) \longrightarrow Pred(S)$ by precomposition.

Given two graphical measurement scenarios:

Simulations $f: S \longrightarrow T$ induce a map $Pred(T) \longrightarrow Pred(S)$ by precomposition.

• Deterministic simulations are pBA homomorphisms $F(T) \longrightarrow F(S)$.

Given two graphical measurement scenarios:

- Simulations $f: S \longrightarrow T$ induce a map $Pred(T) \longrightarrow Pred(S)$ by precomposition.
- Deterministic simulations are pBA homomorphisms $F(T) \longrightarrow F(S)$.
- Adaptive simulations: if-then-else algebras (Dicker).

Given two graphical measurement scenarios:

- Simulations $f: S \longrightarrow T$ induce a map $Pred(T) \longrightarrow Pred(S)$ by precomposition.
- Deterministic simulations are pBA homomorphisms $F(T) \longrightarrow F(S)$.
- ► Adaptive simulations: if-then-else algebras (Dicker).
- More general resolutions of identity: LEP

 $\frac{u \wedge t \equiv u, \ v \wedge \neg t \equiv v}{u \odot v}$

Relativising Logical Bell inequalities

'Logical Bell inequalities', Abramsky & Hardy, Physical Review A, 2012.

• Propositional formulae ϕ_1, \ldots, ϕ_N

- Propositional formulae ϕ_1, \ldots, ϕ_N
- $\blacktriangleright p_i := \operatorname{Prob}(\phi_i)$

- Propositional formulae ϕ_1, \ldots, ϕ_N
- $\blacktriangleright p_i := \mathsf{Prob}(\phi_i)$
- Suppose the ϕ_i are not simultaneously satisfiable. Then Prob $(\bigwedge \phi_i) = 0$.

- Propositional formulae ϕ_1, \ldots, ϕ_N
- $\blacktriangleright p_i := \mathsf{Prob}(\phi_i)$
- Suppose the ϕ_i are not simultaneously satisfiable. Then Prob $(\bigwedge \phi_i) = 0$.
- Using elementary logic and probability:

$$1 = \mathsf{Prob}\left(\neg \bigwedge \phi_i\right)$$

- Propositional formulae ϕ_1, \ldots, ϕ_N
- $\blacktriangleright p_i := \operatorname{Prob}(\phi_i)$
- Suppose the ϕ_i are not simultaneously satisfiable. Then $\operatorname{Prob}(\bigwedge \phi_i) = 0$.
- Using elementary logic and probability:

$$1 = \mathsf{Prob}\left(\neg \bigwedge \phi_i
ight) = \mathsf{Prob}\left(igvee \neg \phi_i
ight)$$

- Propositional formulae ϕ_1, \ldots, ϕ_N
- $\blacktriangleright p_i := \operatorname{Prob}(\phi_i)$
- Suppose the ϕ_i are not simultaneously satisfiable. Then $\operatorname{Prob}(\bigwedge \phi_i) = 0$.
- Using elementary logic and probability:

$$1 = \operatorname{\mathsf{Prob}}\left(\neg \bigwedge \phi_i
ight) = \operatorname{\mathsf{Prob}}\left(\bigvee \neg \phi_i
ight) \, \leq \, \sum_{i=1}^N \operatorname{\mathsf{Prob}}\left(\neg \phi_i
ight)$$

- Propositional formulae ϕ_1, \ldots, ϕ_N
- $\blacktriangleright p_i := \operatorname{Prob}(\phi_i)$
- Suppose the ϕ_i are not simultaneously satisfiable. Then $\operatorname{Prob}(\bigwedge \phi_i) = 0$.
- Using elementary logic and probability:

$$1 = \operatorname{Prob}\left(\neg \bigwedge \phi_i\right) = \operatorname{Prob}\left(\bigvee \neg \phi_i\right) \leq \sum_{i=1}^N \operatorname{Prob}\left(\neg \phi_i\right) = \sum_{i=1}^N (1 - p_i)$$

- Propositional formulae ϕ_1, \ldots, ϕ_N
- $\blacktriangleright p_i := \operatorname{Prob}(\phi_i)$
- Suppose the ϕ_i are not simultaneously satisfiable. Then $\operatorname{Prob}(\bigwedge \phi_i) = 0$.
- Using elementary logic and probability:

$$1 = \operatorname{Prob}\left(\neg \bigwedge \phi_i\right) = \operatorname{Prob}\left(\bigvee \neg \phi_i\right) \leq \sum_{i=1}^{N} \operatorname{Prob}\left(\neg \phi_i\right) = \sum_{i=1}^{N} (1 - p_i) = N - \sum_{i=1}^{N} p_i \quad .$$

'Logical Bell inequalities', Abramsky & Hardy, Physical Review A, 2012.

- Propositional formulae ϕ_1, \ldots, ϕ_N
- $\blacktriangleright p_i := \operatorname{Prob}(\phi_i)$
- Suppose the ϕ_i are not simultaneously satisfiable. Then $\operatorname{Prob}(\bigwedge \phi_i) = 0$.
- Using elementary logic and probability:

$$1 = \operatorname{Prob}\left(\neg \bigwedge \phi_i\right) = \operatorname{Prob}\left(\bigvee \neg \phi_i\right) \leq \sum_{i=1}^{N} \operatorname{Prob}\left(\neg \phi_i\right) = \sum_{i=1}^{N} (1 - p_i) = N - \sum_{i=1}^{N} p_i \quad .$$

Hence,

$$\sum_{i=1}^N p_i \leq N-1$$
 .

Questions...

?