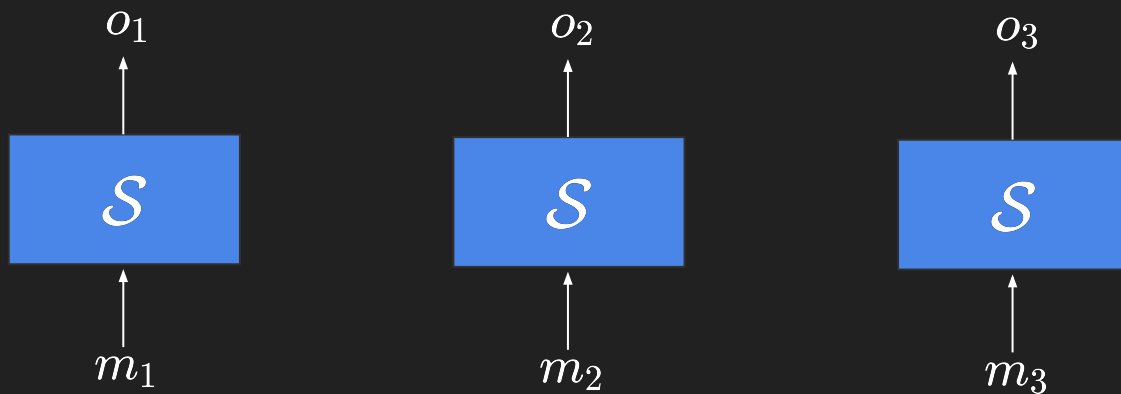


Quantifying Non-Classicality in Temporal Measurement Scenarios

Samson Abramsky, Rui Soares Barbosa, Amy Searle

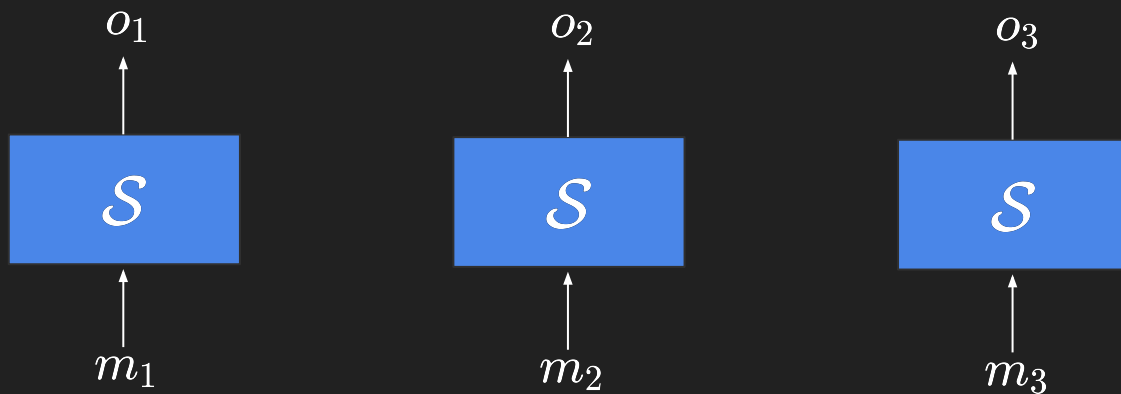
Part 1: The Framework

Setup



Setup

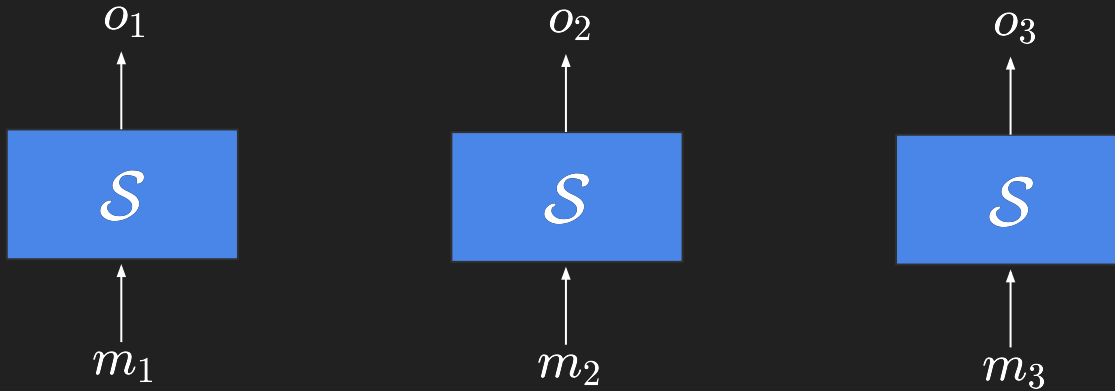
X : Set of measurements



Setup

X : Set of measurements

O : Set of outcomes for each measurement

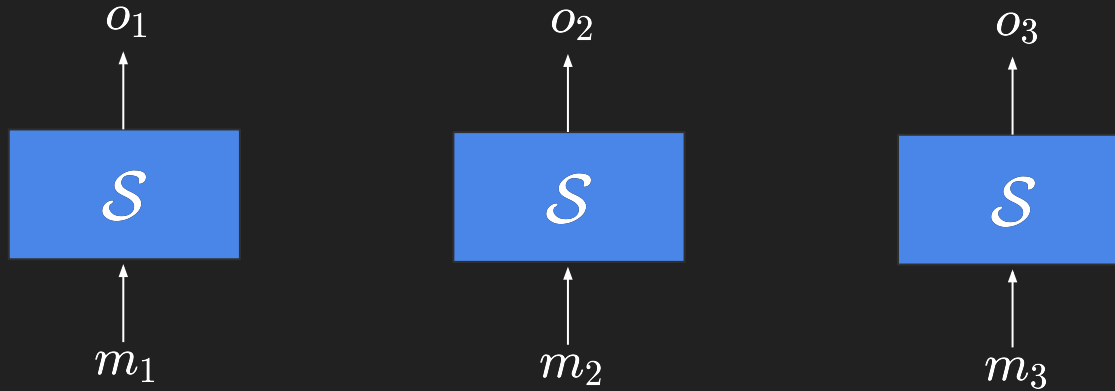


Setup

X : Set of measurements

O : Set of outcomes for each measurement

X^* : Set of all possible sequences of measurements in X



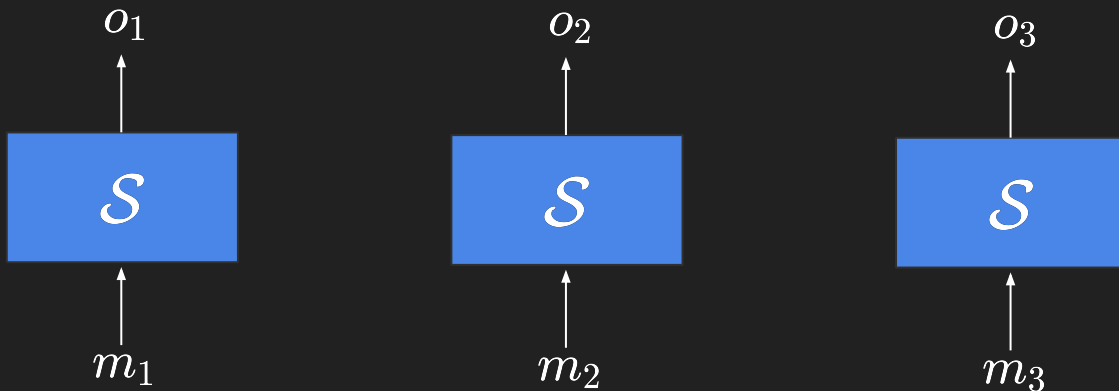
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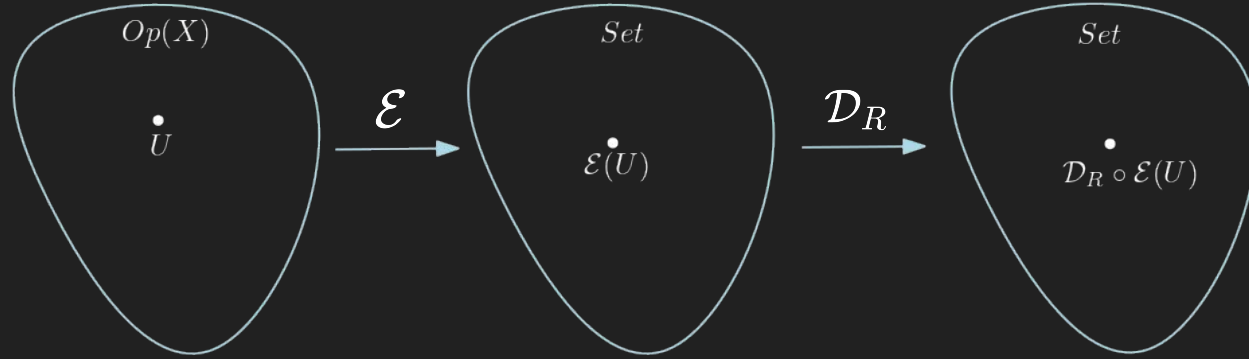
Σ : A left-closed subset of X^*



Motivation

- What constitutes as a *classical system* in this setup is not well understood
- Casting in a sheaf theoretic framework allows us to use tools from sheaf theory
- The sheaf theoretic framework for *spatial* correlations has included
 - Logical Bell Inequalities
 - Contextual Fraction
 - Notions of Simulation
 - Cohomological obstructions to classicality

Presheaves— Notation



$U, U' \dots$: Sets of observables

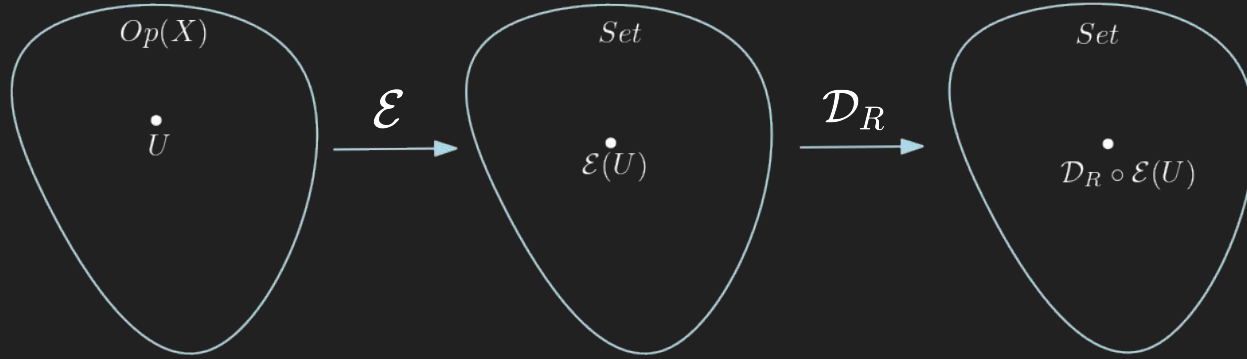
$\mathcal{E}(U), \mathcal{E}(U') \dots$

: Mapping observables to outcomes

$\mathcal{D}_R(\mathcal{E}(U)), \mathcal{D}_R(\mathcal{E}(U')) \dots$

: Probability distributions over these mappings

Presheaves– Notation



$U, U' \dots$: Sets of observables

$x \in U$:

Measurement, Set of Measurements

$\mathcal{E}(U), \mathcal{E}(U') \dots$

: Mapping observables to outcomes

$f \in \mathcal{E}(U)$: Behaviour of the System

$\mathcal{D}_R(\mathcal{E}(U)), \mathcal{D}_R(\mathcal{E}(U')) \dots$

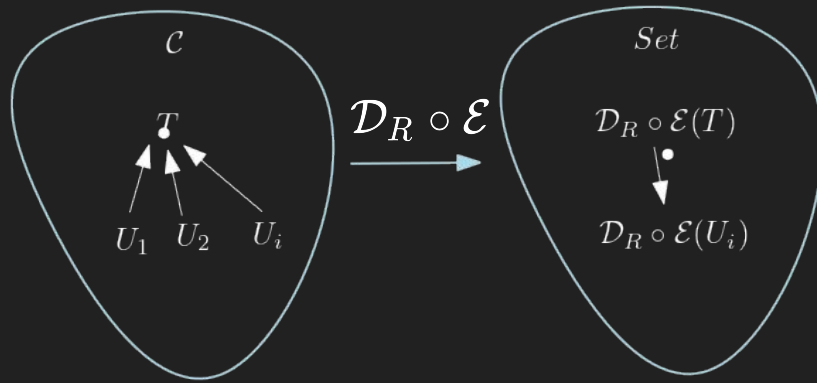
: Probability distributions over these mappings

$e_U \in \mathcal{D}_R \circ \mathcal{E}(U)$:

Probabilistic Behaviour of the System

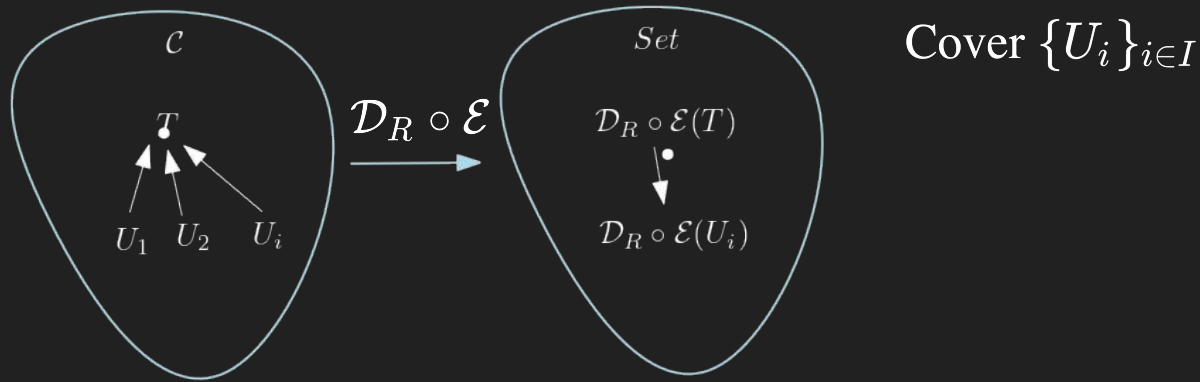
Sheaves

A presheaf is a sheaf when the gluing and uniqueness axioms are satisfied:



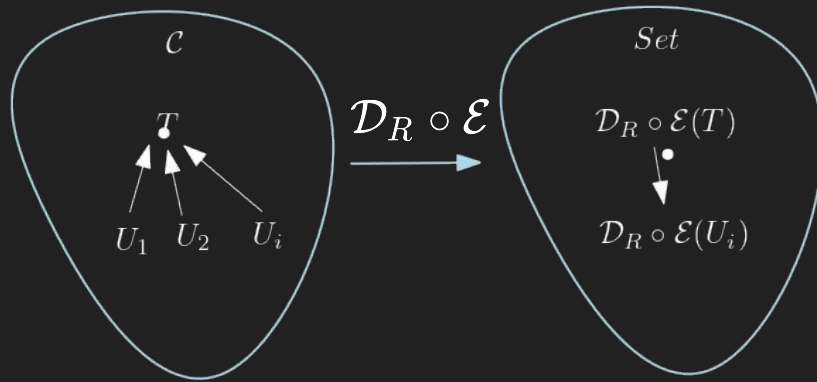
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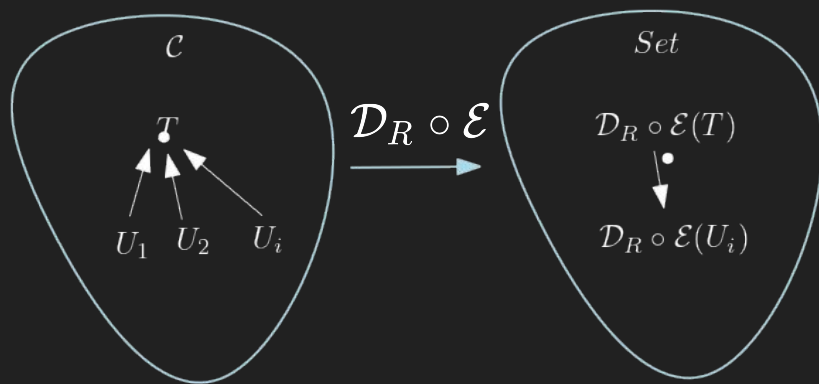


Cover $\{U_i\}_{i \in I}$

Given data $\{e_i \in \mathcal{D}_R \circ \mathcal{E}(U_i)\}_{i \in I}$

Sheaves

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Cover $\{U_i\}_{i \in I}$

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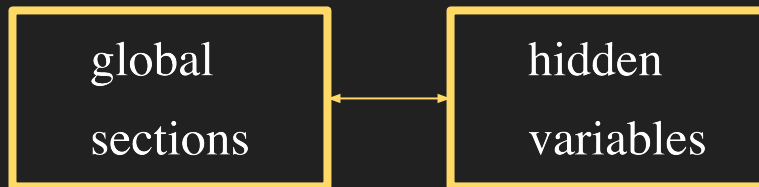
Exists a global section $h \in \mathcal{D}_R \circ \mathcal{E}(T)$

with $h|_{U_i} = e_i$

Sheaves and Classicality

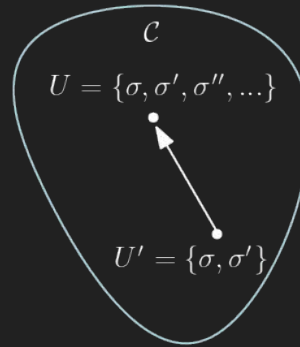
Proposition 3.1. [Abramsky, Brandenburger]:

The existence of a global section for an empirical model implies the existence of a local (or non-contextual) deterministic hidden-variable model which realizes it.



A Sheaf Approach To Temporal Correlations

Step 1: Define the category \mathcal{C}



Objects: Down closed subsets of Σ

Arrows: Subset inclusion

Step 2: Define the map $\mathcal{E} : \mathcal{C} \rightarrow \mathit{Set}$

$$\mathcal{E}(U) = \{f : U \rightarrow \mathcal{O} :: \sigma \mapsto o\}$$

$$\text{lookback}_k(\sigma) = \text{lookback}_k(\sigma') \Rightarrow f(\sigma) = f(\sigma')$$

The Important Bits

Empirical Models

$$\{e_\sigma \in \mathcal{D}_R \circ \mathcal{E}(\sigma)\}_{\sigma \in \Sigma}$$

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Empirical Models

$$\{e_\sigma \in \mathcal{D}_R \circ \mathcal{E}(\sigma)\}_{\sigma \in \Sigma}$$

Classicality

$$h \in \mathcal{D}_R \circ \mathcal{E}(\Sigma) \text{ with } h|_\sigma = e_\sigma \text{ for all } \sigma \in \Sigma$$

Classicality

What does it mean to be classical?

1. Deterministic Classicality

$$\mathcal{E}(\Sigma) = \{f : \Sigma \rightarrow \mathcal{O} :: \sigma \mapsto o\}$$

$$\text{lookback}_k(\sigma) = \text{lookback}_k(\sigma') \Rightarrow f(\sigma) = f(\sigma')$$

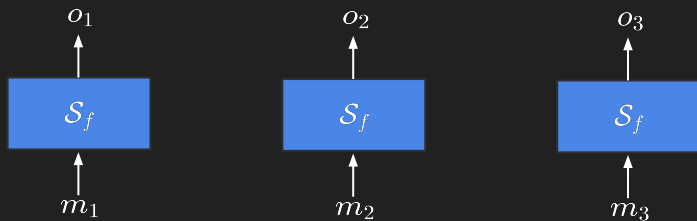
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$$f((m_1)) = o_1$$

$$f((m_1, m_2)) = o_2$$

$$f((m_1, m_2, m_3)) = o_3$$

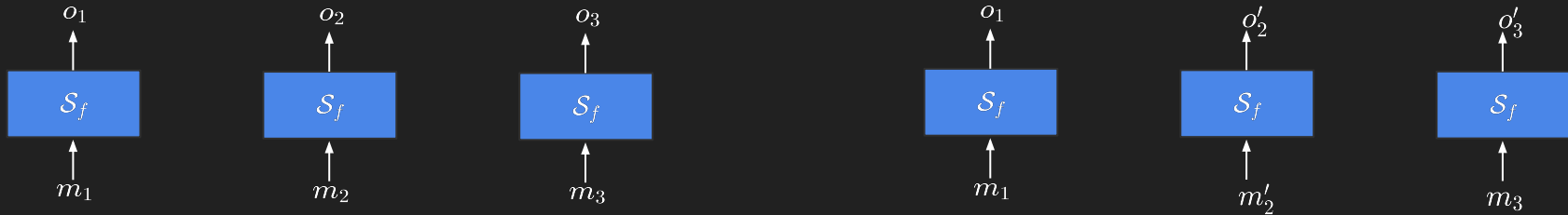
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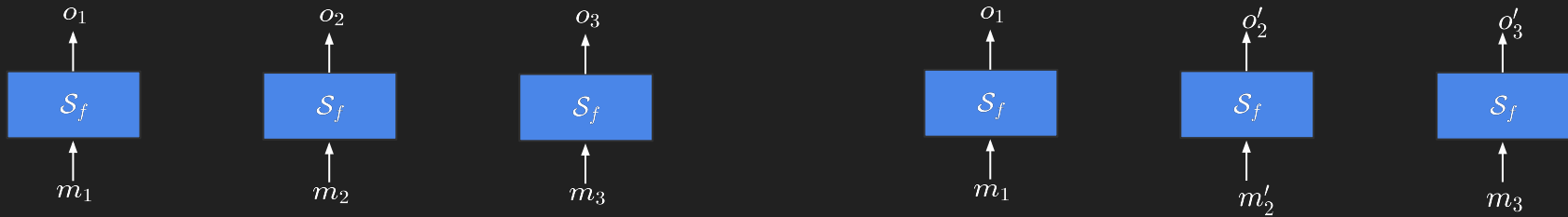
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$$k > 0, \text{ can have } o_3 \neq o'_3$$

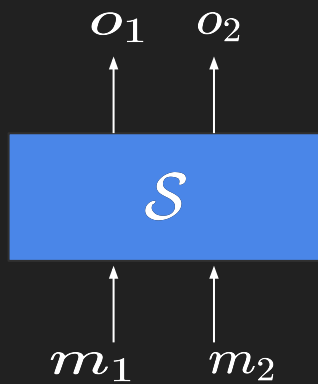
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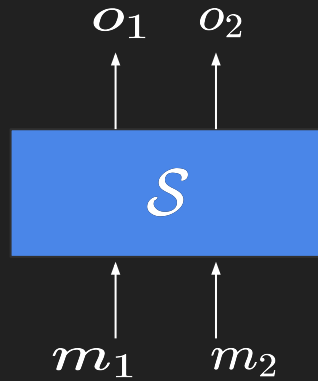
$$f((m_1, m'_2, m_3)) = o'_3$$

Part 2: The Mapping

Contextuality Setup

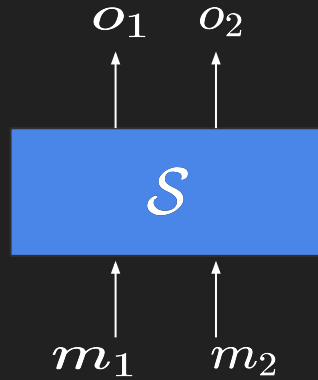


Contextuality Setup



X : Set of measurements

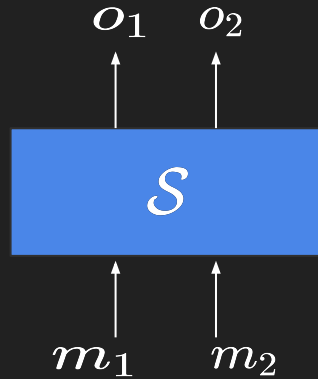
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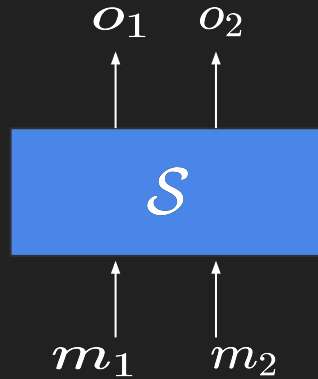


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Contextuality Setup



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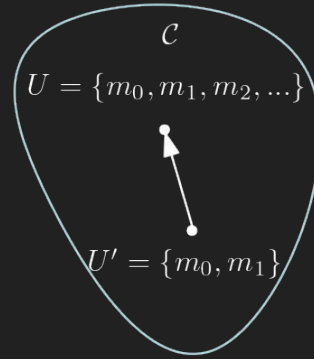
O : Set of outcomes for each measurement

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Note: Σ is a simplicial complex in this case

A Sheaf Approach to Contextuality Correlations

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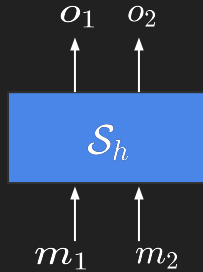
$$\mathcal{E}(U) = O^U = \{s : U \rightarrow O :: m \mapsto o\}$$

Classicality

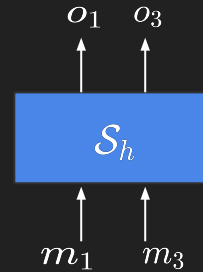
What does it mean to be classical?

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$$\mathcal{E}(X) = \{h : X \rightarrow O :: m \mapsto o\}$$



$$h(m_1) = o_1, h(m_2) = o_2$$



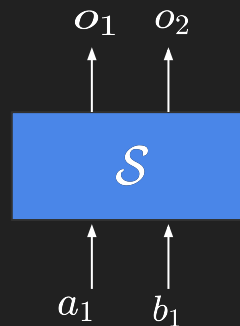
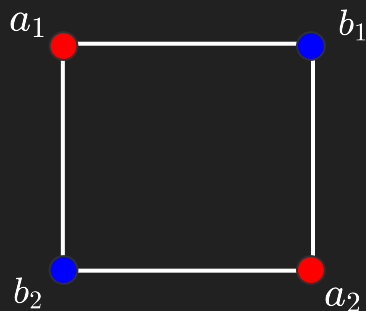
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Vorob'ev's Theorem for Contextuality Setups

Proposition [Vorobev, Barbosa]:

Let Σ be a simplicial complex. Then any empirical model defined on Σ is extendable if and only if Σ is acyclic

Example: CHSH

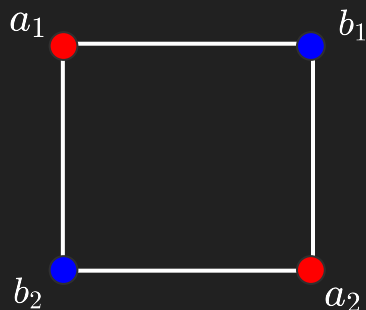


Vorob'ev's Theorem for Contextuality Setups

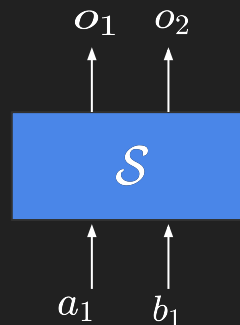
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Not acyclic so
there can be a
contextual
empirical model!



Mapping Scenarios for $k = \infty$

$$\mathcal{C}_\infty : \mathbf{EM}(\mathcal{M}) \rightarrow \mathbf{EM}(\mathcal{M}')$$

$$1. X' := \Sigma$$

$$2. U' \in \Sigma' \iff \bigcup_{\sigma \in U'} \sigma \in \Sigma$$

$$3. O_{(m_0, m_1, \dots, m_k)} := O_{m_k}$$

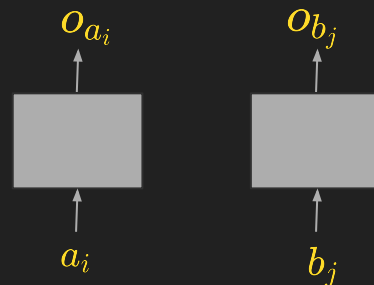
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Example:

$$X' = \{(a_1, b_1), (a_1, b_2), (a_2, b_1), (a_2, b_2), (a_1), (a_2)\}$$

$$\{(a_1), (a_1, b_1)\} \in \Sigma'$$

$$O_{(a_1, b_1)} = O \times O = \{(0, 0), (0, 1), (1, 0), (1, 1)\}$$

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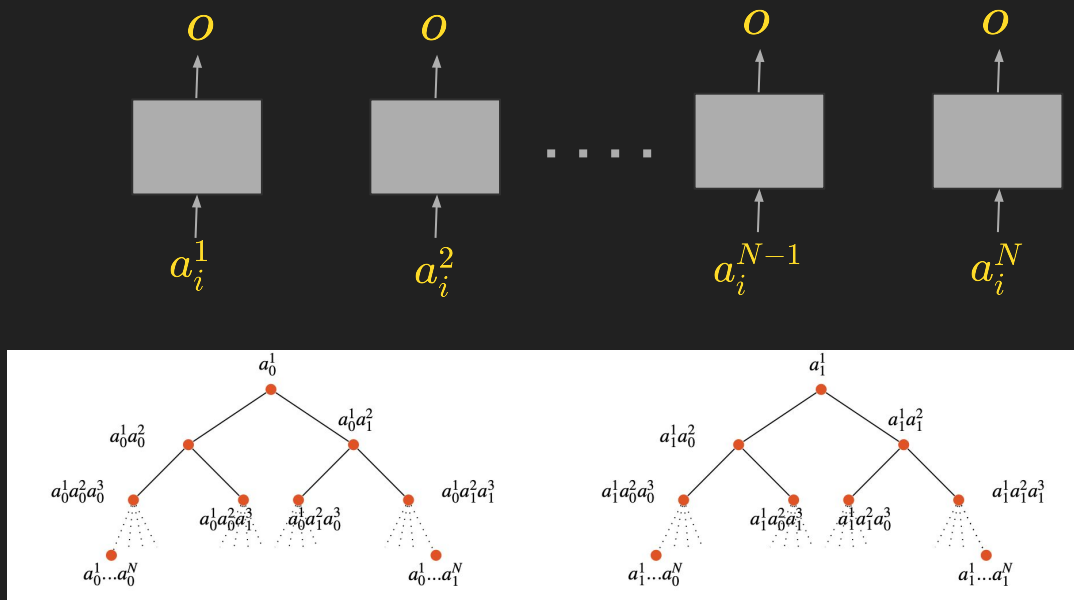
Theorem 3.2. For lookback depth $k = \infty$, there is a map \mathcal{C}_∞ from temporal measurement scenarios to contextuality measurement scenarios, which lifts to empirical models as a convex function $\mathcal{C}_\infty: \mathbf{EM}_\infty \rightarrow \mathbf{EM}(\mathcal{C}_\infty(\mathcal{M}))$ mapping each ∞ -lookback empirical model e on the temporal scenario \mathcal{M} , to an empirical model $\mathcal{C}_k(e)$ on the measurement scenario $\mathcal{C}_\infty(\mathcal{M})$. This map preserves and reflects nonclassicality, meaning that an empirical model e on \mathcal{M} is not ∞ -lookback classical if and only if $\mathcal{C}_\infty(e)$ is contextual.

No Quantum Advantage for $k = \infty$

Proposition: Given any temporal measurement scenario \mathcal{M} every empirical model $e \in EM(\mathcal{M})$ is ∞ -lookback classical.

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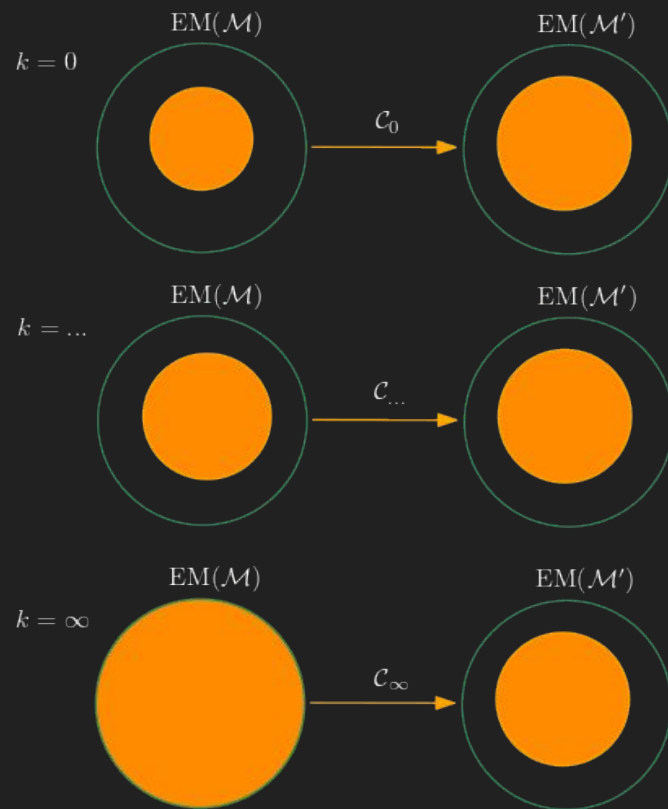


A (Still Speculative) More General Mapping

$$\mathcal{C}_k : \mathbf{EM}(\mathcal{M}) \rightarrow \mathbf{EM}(\mathcal{M}')$$

1. $X' := \{(m, h) \mid m \in X, \exists \sigma = (\dots, m) \in \Sigma. h \in \text{lookback}_k(\sigma)\}$
2. $U' \in \Sigma' \iff \exists \sigma \in \Sigma. \forall (m, (m_0, \dots, m_l)) \in U'. (m_0, \dots, m_l, m) \subseteq \sigma$
3. $O_{(m,h)} := O_m$

Visualising this Mapping



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